

Duality

How do we get an upper bound to a maximization LP?

$$\begin{aligned} \max \quad & 13a + 23b \\ \text{s.t.} \quad & 5a + 15b \leq 480 \\ & 4a + 4b \leq 160 \\ & 35a + 20b \leq 1190 \\ & a, b \geq 0 \end{aligned}$$

Note that a lower bound is easy to derive. Every choice of $a, b \geq 0$ gives us a lower bound (e.g. $a = 12, b = 28$ gives us a lower bound of 800).

If you take a conic combination of the rows (multiply the i -th row with $y_i \geq 0$) such that $\sum_i y_i a_{ij} \geq c_j$ then $\sum_i y_i b_i$ will be an upper bound.

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Definition 2

Let $z = \max\{c^T x \mid Ax \leq b, x \geq 0\}$ be a linear program P (called the primal linear program).

The linear program D defined by

$$w = \min\{b^T y \mid A^T y \geq c, y \geq 0\}$$

is called the **dual problem**.

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Lemma 3

The dual of the dual problem is the primal problem.

Proof:

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Weak Duality

Let $z = \max\{c^T x \mid Ax \leq b, x \geq 0\}$ and
 $w = \min\{b^T y \mid A^T y \geq c, y \geq 0\}$ be a primal dual pair.

x is primal feasible iff $x \in \{x \mid Ax \leq b, x \geq 0\}$

y is dual feasible, iff $y \in \{y \mid A^T y \geq c, y \geq 0\}$.

Theorem 4 (Weak Duality)

Let \hat{x} be primal feasible and let \hat{y} be dual feasible. Then

$$c^T \hat{x} \leq z \leq w \leq b^T \hat{y} .$$

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This gives

$$c^T \hat{x} \leq y^T A \hat{x} \leq b^T y .$$

Since, there exists primal feasible \hat{x} with $c^T \hat{x} = z$, and dual feasible \hat{y} with $b^T \hat{y} = w$ we get $z \leq w$.

If P is unbounded then D is infeasible.

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5.2 Simplex and Duality

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Primal:

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Dual:

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Proof of Optimality Criterion for Simplex

Suppose that we have a basic feasible solution with **reduced cost**

$$\tilde{c} = c^T - c_B^T A_B^{-1} A \leq 0$$

This is equivalent to $A^T (A_B^{-1})^T c_B \geq c$

$y^* = (A_B^{-1})^T c_B$ is solution to the **dual** $\min\{b^T y \mid A^T y \geq c\}$.

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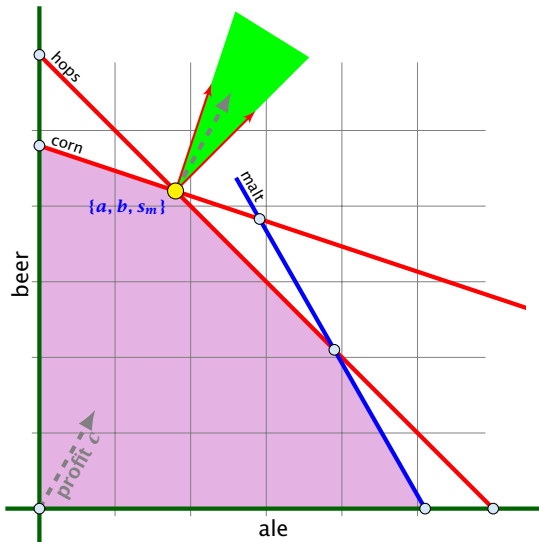
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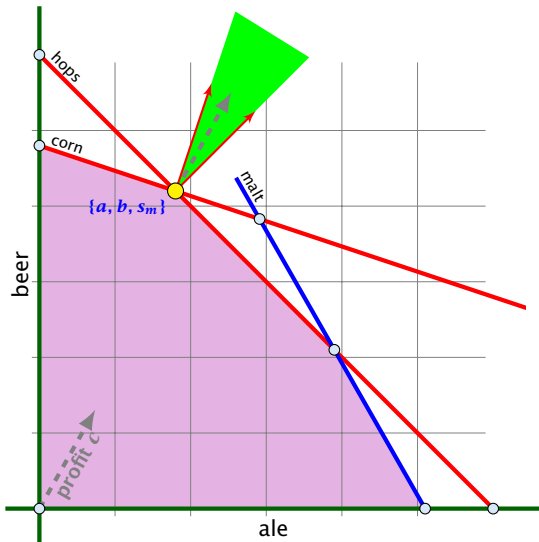
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Strong Duality

Theorem 5 (Strong Duality)

Let P and D be a primal dual pair of linear programs, and let z^* and w^* denote the optimal solution to P and D , respectively.

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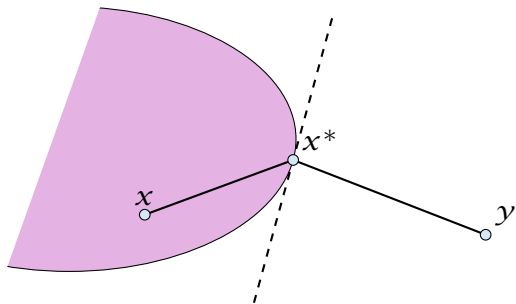
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Lemma 7 (Weierstrass)

Let X be a compact set and let $f(x)$ be a continuous function on X . Then $\min\{f(x) : x \in X\}$ exists.

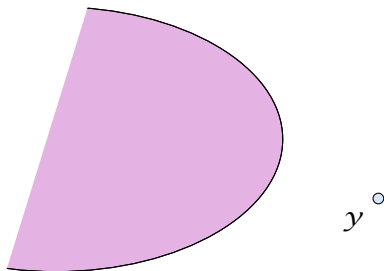
Lemma 8 (Projection Lemma)

Let $X \subseteq \mathbb{R}^m$ be a non-empty convex set, and let $y \notin X$. Then there exist $x^* \in X$ with minimum distance from y . Moreover for all $x \in X$ we have $(y - x^*)^T(x - x^*) \leq 0$.



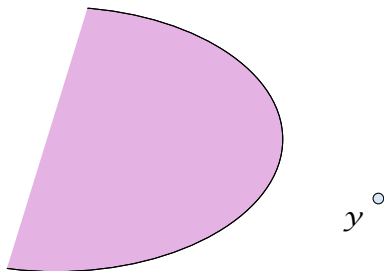
Proof of the Projection Lemma

- ▶ Define $f(x) = \|y - x\|$.
- ▶ We want to apply Weierstrass but X may not be bounded.
- ▶ $X \neq \emptyset$. Hence, there exists $x' \in X$.
- ▶ Define $X' = \{x \in X \mid \|y - x\| \leq \|y - x'\|\}$. This set is closed and bounded.
- ▶ Applying Weierstrass gives the existence.



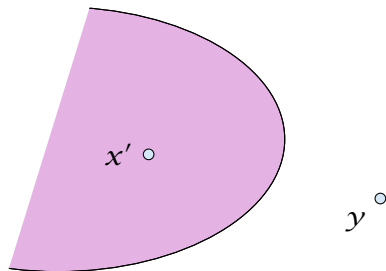
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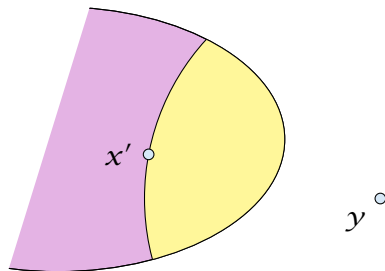
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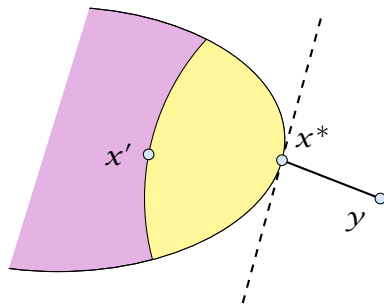
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- ▶ Applying Weierstrass gives the existence.



Proof of the Projection Lemma (continued)

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x^* is minimum. Hence $\|y - x^*\|^2 \leq \|y - x\|^2$ for all $x \in X$.

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$$\|y - x^*\|^2 \leq \|y - x^* - \epsilon(x - x^*)\|^2$$

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$$\begin{aligned}\|y - x^*\|^2 &\leq \|y - x^* - \epsilon(x - x^*)\|^2 \\ &= \|y - x^*\|^2 + \epsilon^2 \|x - x^*\|^2 - 2\epsilon(y - x^*)^T(x - x^*)\end{aligned}$$

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Hence, $(y - x^*)^T(x - x^*) \leq \frac{1}{2}\epsilon \|x - x^*\|^2$.

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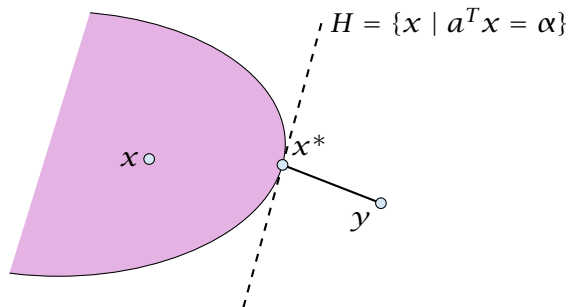
Letting $\epsilon \rightarrow 0$ gives the result.

Theorem 9 (Separating Hyperplane)

Let $X \subseteq \mathbb{R}^m$ be a non-empty closed convex set, and let $y \notin X$. Then there exists a *separating hyperplane* $\{x \in \mathbb{R}^m : a^T x = \alpha\}$ where $a \in \mathbb{R}^m$, $\alpha \in \mathbb{R}$ that *separates* y from X . ($a^T y < \alpha$; $a^T x \geq \alpha$ for all $x \in X$)

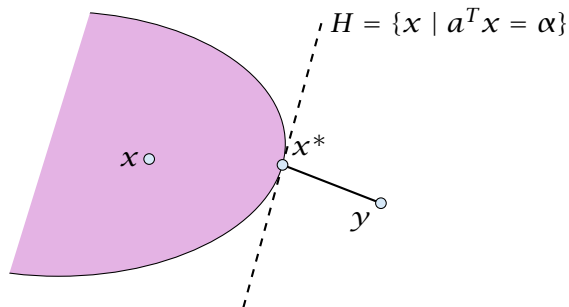
Proof of the Hyperplane Lemma

- ▶ Let $x^* \in X$ be closest point to y in X .
- ▶ By previous lemma $(y - x^*)^T(x - x^*) \leq 0$ for all $x \in X$.
- ▶ Choose $a = (x^* - y)$ and $\alpha = a^T x^*$.
- ▶ For $x \in X$: $a^T(x - x^*) \geq 0$, and, hence, $a^T x \geq \alpha$.
- ▶ Also, $a^T y = a^T(x^* - a) = \alpha - \|a\|^2 < \alpha$



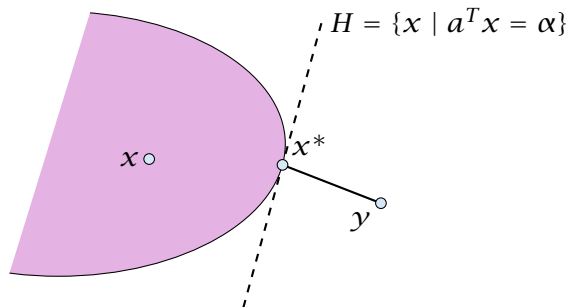
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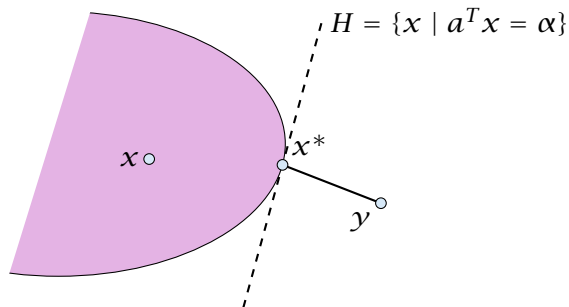
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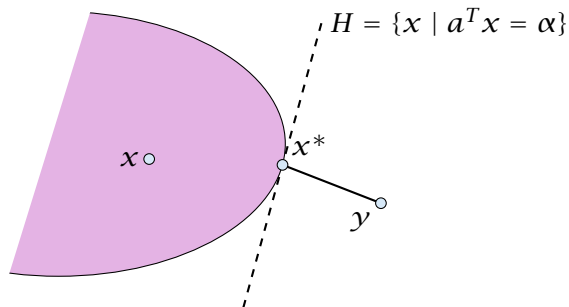
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Lemma 10 (Farkas Lemma)

Let A be an $m \times n$ matrix, $b \in \mathbb{R}^m$. Then *exactly one* of the following statements holds.

1. $\exists x \in \mathbb{R}^n$ with $Ax = b$, $x \geq 0$
2. $\exists y \in \mathbb{R}^m$ with $A^T y \geq 0$, $b^T y < 0$

Assume \hat{x} satisfies 1. and \hat{y} satisfies 2. Then

$$0 > \hat{y}^T b = \hat{y}^T A \hat{x} \geq 0$$

Hence, at most one of the statements can hold.

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Proof of Farkas Lemma

Now, assume that 1. does not hold.

Consider $S = \{Ax : x \geq 0\}$ so that S closed, convex, $b \notin S$.

We want to show that there is y with $A^T y \geq 0$, $b^T y < 0$.

Let y be a hyperplane that separates b from S . Hence, $y^T b < \alpha$ and $y^T s \geq \alpha$ for all $s \in S$.

$$0 \in S \Rightarrow \alpha \leq 0 \Rightarrow y^T b < 0$$

$y^T Ax \geq \alpha$ for all $x \geq 0$. Hence, $y^T A \geq 0$ as we can choose x arbitrarily large.

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Lemma 11 (Farkas Lemma; different version)

Let A be an $m \times n$ matrix, $b \in \mathbb{R}^m$. Then exactly one of the following statements holds.

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Rewrite the conditions:

1. $\exists x \in \mathbb{R}^n$ with $\begin{bmatrix} A & I \end{bmatrix} \cdot \begin{bmatrix} x \\ s \end{bmatrix} = b, x \geq 0, s \geq 0$
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Proof of Strong Duality

$$P: z = \max\{c^T x \mid Ax \leq b, x \geq 0\}$$

$$D: w = \min\{b^T y \mid A^T y \geq c, y \geq 0\}$$

Theorem 12 (Strong Duality)

Let P and D be a primal dual pair of linear programs, and let z and w denote the optimal solution to P and D , respectively (i.e., P and D are non-empty). Then

$$z = w .$$

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$$\begin{array}{l} \exists x \in \mathbb{R}^n \\ \text{s.t.} \quad Ax \leq b \\ \quad \quad -c^T x \leq -\alpha \\ \quad \quad x \geq 0 \end{array}$$

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$$\exists x \in \mathbb{R}^n$$

$$\begin{aligned} \text{s.t.} \quad Ax &\leq b \\ -c^T x &\leq -\alpha \\ x &\geq 0 \end{aligned}$$

$$\exists y \in \mathbb{R}^m; v \in \mathbb{R}$$

$$\begin{aligned} \text{s.t.} \quad A^T y - cv &\geq 0 \\ b^T y - \alpha v &< 0 \\ y, v &\geq 0 \end{aligned}$$

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From the definition of α we know that the first system is infeasible; hence the second must be feasible.

Proof of Strong Duality

$$\begin{aligned} \exists \mathbf{y} \in \mathbb{R}^m; \mathbf{v} \in \mathbb{R} \\ \text{s.t.} \quad A^T \mathbf{y} - \mathbf{v} &\geq 0 \\ \mathbf{b}^T \mathbf{y} - \alpha \mathbf{v} &< 0 \\ \mathbf{y}, \mathbf{v} &\geq 0 \end{aligned}$$

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If the solution \mathbf{y}, \mathbf{v} has $\mathbf{v} = 0$ we have that

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is feasible. By Farkas lemma this gives that LP P is infeasible. Contradiction to the assumption of the lemma.

Proof of Strong Duality

Hence, there exists a solution y, v with $v > 0$.

We can rescale this solution (scaling both y and v) s.t. $v = 1$.

Then y is feasible for the dual but $b^T y < \alpha$. This means that $w < \alpha$.

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Fundamental Questions

Definition 13 (Linear Programming Problem (LP))

Let $A \in \mathbb{Q}^{m \times n}$, $b \in \mathbb{Q}^m$, $c \in \mathbb{Q}^n$, $\alpha \in \mathbb{Q}$. Does there exist $x \in \mathbb{Q}^n$ s.t. $Ax = b$, $x \geq 0$, $c^T x \geq \alpha$?

Questions:

- ▶ Is LP in NP?
- ▶ Is LP in co-NP? yes!
- ▶ Is LP in P?

Proof:

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Proof:

- ▶ Given a primal maximization problem P and a parameter α . Suppose that $\alpha > \text{opt}(P)$.
- ▶ We can prove this by providing an optimal basis for the dual.
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Complementary Slackness

Lemma 14

Assume a linear program $P = \max\{c^T x \mid Ax \leq b; x \geq 0\}$ has solution x^* and its dual $D = \min\{b^T y \mid A^T y \geq c; y \geq 0\}$ has solution y^* .

1. If $x_j^* > 0$ then the j -th constraint in D is tight.
2. If the j -th constraint in D is not tight then $x_j^* = 0$.
3. If $y_i^* > 0$ then the i -th constraint in P is tight.
4. If the i -th constraint in P is not tight then $y_i^* = 0$.

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2. If the j -th constraint in D is not tight then $x_j^* = 0$.
3. If $y_i^* > 0$ then the i -th constraint in P is tight.
4. If the i -th constraint in P is not tight then $y_i^* = 0$.

If we say that a variable x_j^* (y_i^*) has slack if $x_j^* > 0$ ($y_i^* > 0$), (i.e., the corresponding variable restriction is not tight) and a constraint has slack if it is not tight, then the above says that for a primal-dual solution pair it is not possible that a constraint **and** its corresponding (dual) variable has slack.

Proof: Complementary Slackness

Analogous to the proof of weak duality we obtain

$$c^T x^* \leq y^{*T} A x^* \leq b^T y^*$$

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From the constraint of the dual it follows that $y^T A \geq c^T$. Hence the left hand side is a sum over the product of non-negative numbers. Hence, if e.g. $(y^T A - c^T)_j > 0$ (the j -th constraint in the dual is not tight) then $x_j = 0$ (2.). The result for (1./3./4.) follows similarly.

Interpretation of Dual Variables

- ▶ Brewer: find mix of ale and beer that maximizes profits

$$\begin{aligned} \max \quad & 13a + 23b \\ \text{s.t.} \quad & 5a + 15b \leq 480 \\ & 4a + 4b \leq 160 \\ & 35a + 20b \leq 1190 \\ & a, b \geq 0 \end{aligned}$$

- ▶ Entrepreneur: buy resources from brewer at minimum cost
 C, H, M : unit price for corn, hops and malt.

$$\begin{aligned} \min \quad & 480C + 160H + 1190M \\ \text{s.t.} \quad & 5C + 4H + 35M \geq 13 \\ & 15C + 4H + 20M \geq 23 \\ & C, H, M \geq 0 \end{aligned}$$

Note that brewer won't sell (at least not all) if e.g.
 $5C + 4H + 35M < 13$ as then brewing ale would be advantageous.

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 C, H, M : unit price for corn, hops and malt.

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- ▶ How much money is the brewer willing to pay for additional amount of Corn, Hops, or Malt?
- ▶ We are interested in the marginal price, i.e., what happens if we increase the amount of Corn, Hops, and Malt by ϵ_C , ϵ_H , and ϵ_M , respectively.

The profit increases to $\max\{c^T x \mid Ax \leq b + \epsilon; x \geq 0\}$. Because of strong duality this is equal to

$$\begin{array}{ll} \min & (b^T + \epsilon^T)y \\ \text{s.t.} & A^T y \geq c \\ & y \geq 0 \end{array}$$

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If ϵ is “small” enough then the optimum dual solution y^* might not change. Therefore the profit increases by $\sum_i \epsilon_i y_i^*$.

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Interpretation of Dual Variables

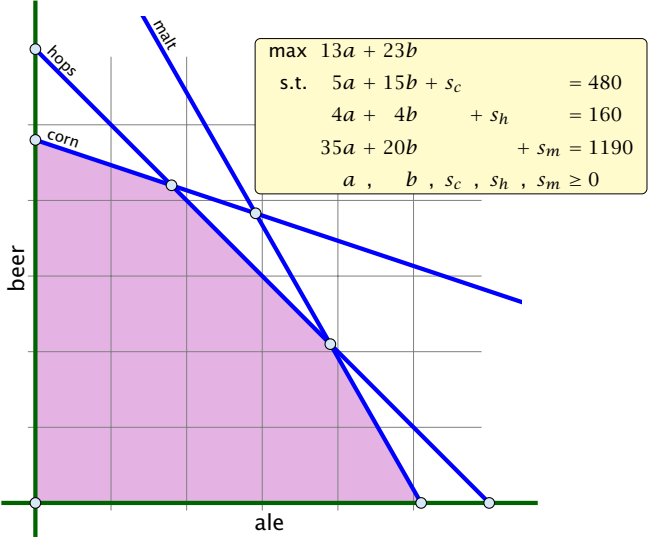
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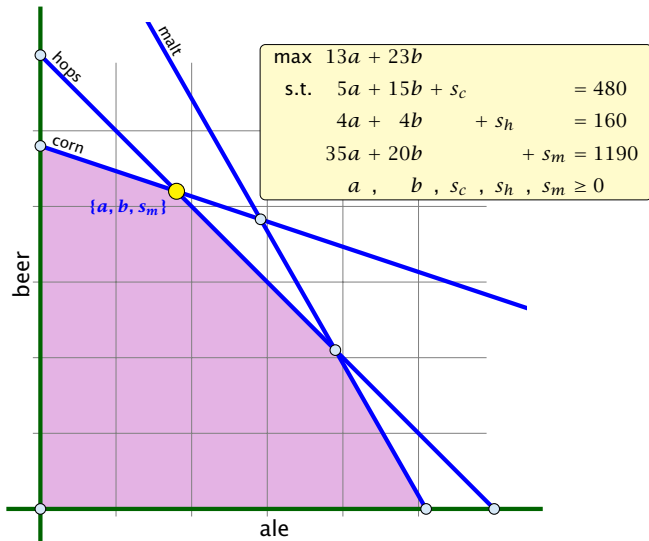
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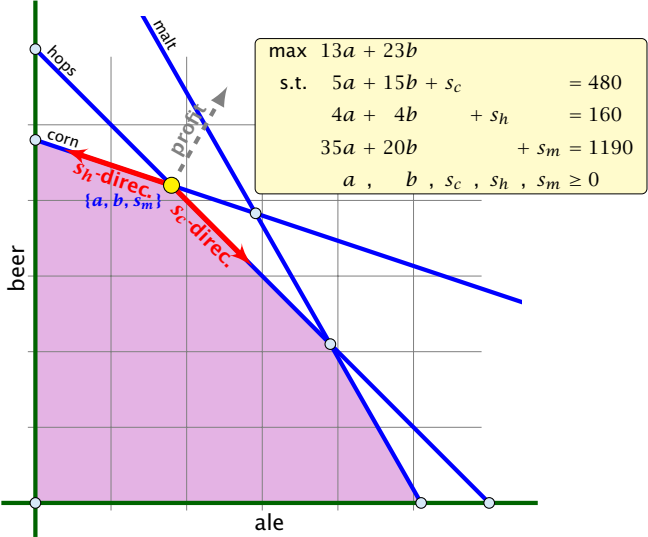
Example



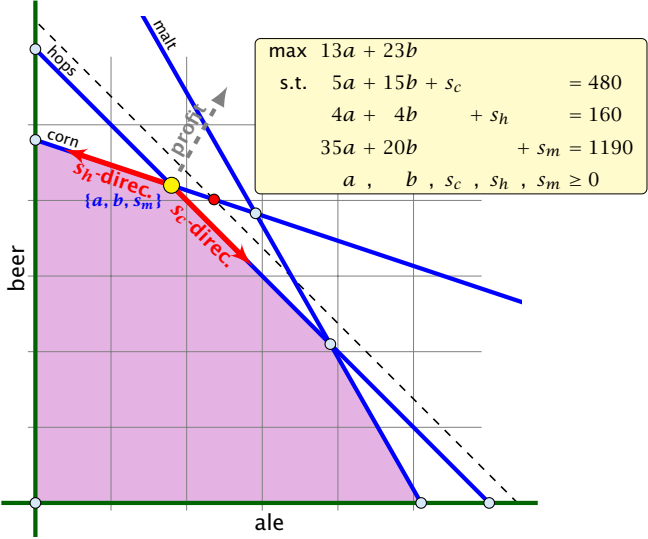
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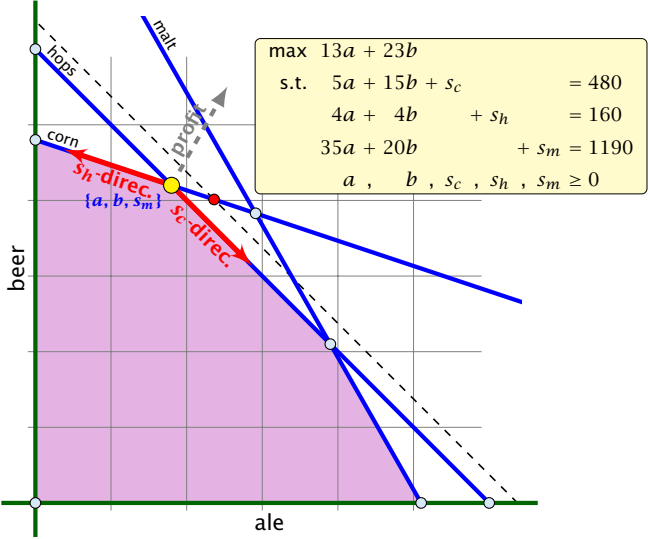
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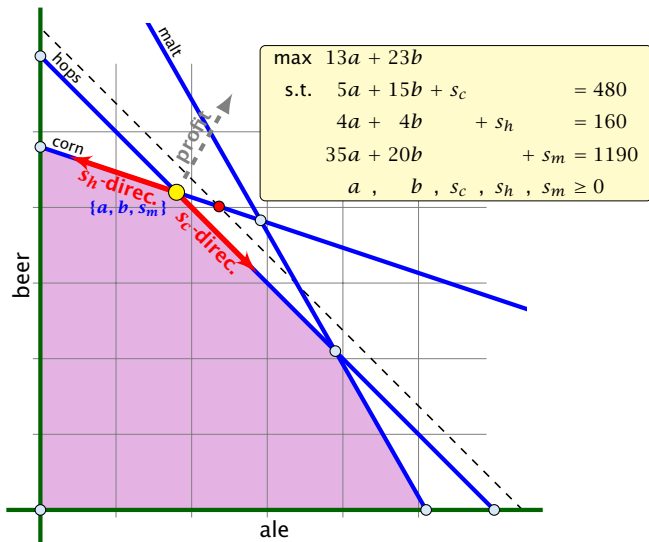
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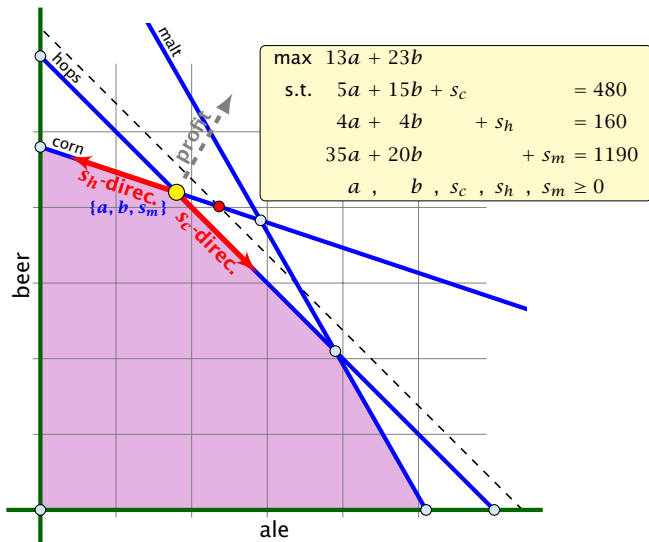
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$$= c_B^T A_B^{-1} e_h.$$

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Of course, the previous argument about the increase in the primal objective only holds for the non-degenerate case.

If the optimum basis is degenerate then increasing the supply of one resource may not allow the objective value to increase.

Flows

Definition 15

An (s, t) -flow in a (complete) directed graph $G = (V, V \times V, c)$ is a function $f : V \times V \rightarrow \mathbb{R}_0^+$ that satisfies

1. For each edge (x, y)

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